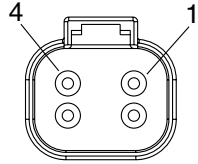


Wiring diagram

Connector DT04-4P

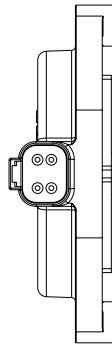
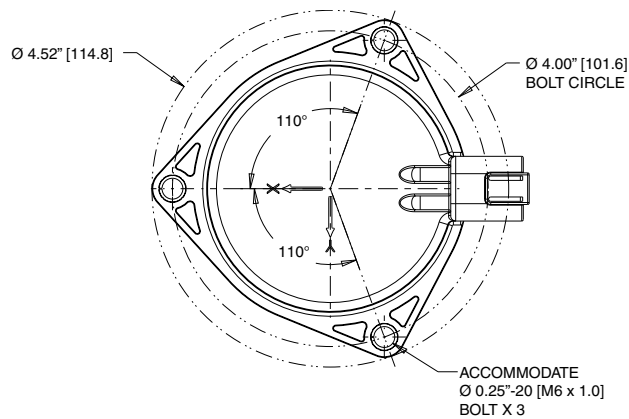


- 1 +BAT (+12 V, +24 V)
- 2 -BAT (Ground)
- 3 CAN-L
- 4 CAN-H

Mating connector: DT06-4S
W4S
1062-16-0144

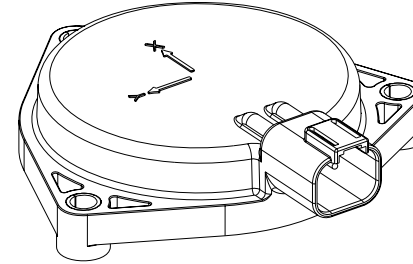
Notes:

1. Recommended mounting bolt diameter 1/4" or M6.
2. Do not exceed specified torque limit, 135 in-lbs [15.3 Nm].



Installation UTS

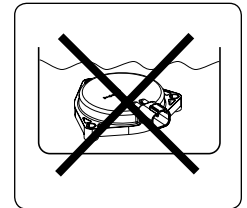
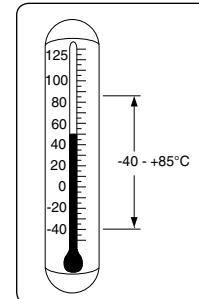
Publ.no: HY33-2374-IS
Ed. 09/2016



NOTICE

Sensor communicates over CAN bus using SAE J1939 protocol.

- CAN bus speed 250 kbps
- CAN source address 0xE2
- Data broadcast rate 10 Hz ($\pm 10^\circ$), 50 Hz ($\pm 90^\circ$)
- Refer to part drawing for CAN message specification



For further information see:
Catalog HY33-2374/US

WARNING

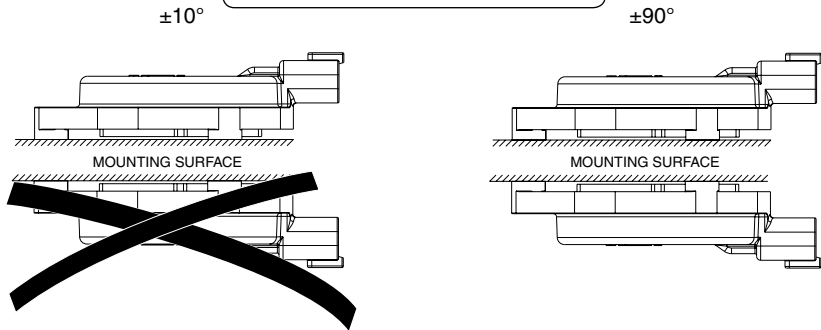
FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS AND/OR SYSTEMS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

This document and other information from Parker Hannifin Corporation, its subsidiaries and authorized distributors provide product and/or system options for further investigation by users having technical expertise. It is important that you analyze all aspects of your application, including consequences of any failure, and review the information concerning the product or system in the current product catalog. Due to the variety of operating conditions and applications for these products or systems, the user, through its own analysis and testing, is solely responsible for making the final selection of the products and systems and assuring that all performance, safety and warning requirements of the application are met.

The products described herein, including without limitation, product features, specifications, designs, availability and pricing, are subject to change by Parker Hannifin Corporation and its subsidiaries at any time without notice.



NOTICE
 Sensor should be mounted on a flat surface ($\nabla .010''$ max).
 • $\pm 10^\circ$ sensors must be mounted 'right side up'
 • $\pm 90^\circ$ sensors may be mounted 'right side up' or 'upside down'



$\pm 90^\circ$ 2 and 3 axis sensor outputs at various orientations

